

MIDILIFT SL+

ELECTRICAL WIRING MANUAL

ISSUE:

THIS MANUAL IS TO BE LEFT WITH THE FOLLOWING CONTRACT:

STANNAH PART NO: 916143

Stannah

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REV B: FIRE ALARM INPUT ADDED AND IMPORTANT NOTE. JN 27/05/14 ECN A5573.























	NAME: J.NICHOLLS	DATE: 16/08/12
	CHECKED: M.HOOD	DATE: 16/08/12
	RESET SWITCH AND ENCODER CONNECTION DETAILS	
	Stannah	HEAD OFFICE: Anton Mill Andover Hampshire SP10 2NX England Tel: 01264 339090 Fax: 337942
REV A: RESET AND RESET SLOW SWITCHES CHANGED TO ROCKER SWITCH. MH 08/03/16 A5735.	DRAWING NO: 9448-057	' REV: A





CARRIAGE DIGITAL DISPLAY UNIT











REV B: UPDATED FOR NEW LOGO AND TEXT FONT. 01/10/10 JN REV A: SHUTDOWN KEYSWITCH DETAILS REMOVED 11/06/09 MH

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REV: B















DRAWING NO: 9448-060

REV: A







REV A: SECURITY SYSTEM BY OTHERS ADDED. ECN A5688 JN 03/09/15













MEMCO GSM - Quick setup guide

For full details refer to the 'DPC Installation Guide' which can be accessed on the Avire website (www.avire-global.com)

IMPORTANT NOTE: MAINS SUPPLY SHOULD BE DISCONNECTED BEFORE BEGINNING THIS PROCEDURE.

SETTING UP THE DEVICE 1.

A. Insert SIM card into plug J4, pressing it in until it clicks.

- B. Ensure that the antenna is securely connected to plug J2.
- C. Connect the pre-wired battery lead to plug J3.

CHECKING THE NETWORK COVERAGE 2.

A.Ensure all previous steps have been completed.

- B. Turn the first dip switch SW1 to On.
- C. The five LEDs on the front will show the network signal level.
- D.Once a suitable location has been found, switch SW1 to OFF and fix in position.

WIRING THE GSM 3.

A.Connect the mains power supply to plug J6.

- B. Phone line connection between plug J9 (GSM unit) and CM1/CM2 (lift trailer PCB) as per below:
 - J9 terminal 1 to CM2.
 - J9 terminal 2 to CM1.

CONFIGURING THE GSM (via local telephone mode) 4.

- A.Connect an analogue telephone handset into J1A.
- B. Pick up the handset and after hearing the dial tone, enter the access command *#*1234*#*.
- C. Change parameter value P020 to value 00, by entering the following combination on the handset keypad *020#00#.
- D. Hang up the phone to complete configuration.

NAME: J.NICHOLLS	DATE: 02/08/18		
CHECKED: M.HOOD	DATE: 02/08/18		
MIDILIFT			
MEMCO GSM (DCP UNIT)			
WIRING / SETUP GUIDE			
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DRAWING NO: 9452044	REV: A		



REV A: REFERENCE TO RUNNING THE LIFT IN INSTALLATION MODE. 08/07/2013 JN

APPENDIX B – FAULT CODE LIST

Certain fault conditions will cause the controller to latch the lift out of service. When this happens, the relevant fault code will be displayed on all lift digital display units (DDU's) and the lift will be latched out of service.

The lift supply will need to be cycled in order to clear the latch fault and return the lift to normal service (NOTE: After supply has been re-instated the lift will 'RESET' to the bottom floor).

FAULT CODES:	
DDU DISPLAY	DESCRIPTION
A	 ENCODER MOVEMENT FAULT No encoder movement was detected during last run attempt. If lift moved (i.e. is away from floor level) then check encoder assembly for fault. If lift did not move (i.e. is at floor level) then check run circuit for fault.
В	JOURNEY TIME FAULT Maximum journey time exceeded. Check inverter/drive system for errors. Confirm journey time selection using SWITCH 2. • ON = 30 sec (SL+ / PICCOLO DIRECT) 70 sec (PICCOLO 2:1) • OFF = 60 sec (SL+ / PICCOLO DIRECT) 120 sec (PICCOLO 2:1)
С	 LIGHT RAY FAULT Lift controller failed to detect a light ray input during the last 10 consecutive door open commands. Check for misuse of lift. Possible faulty light ray – monitor 'DRM' input with light ray activated.
D/J	RUN CONTACT FAULT Run contact monitor input received whilst lift is stationary. Check the following – • Wiring of 'MC' contactor. • Faulty 'MC' contactor (i.e. permanently energised).
E	 ANTI-SURF FAULT (landing door beaks) Landing door has been manually released whilst lift in normal service. Fault can also occur if door beak contacts have gone out of alignment. Check the following – Misuse of lift. Landing door beak alignment.
F	 ANTI-CREEP RELAY FAULT Controller has detected an input to terminal 'ACM' (Anti-Creep Monitor) when <u>not</u> in anti-creep mode. Check the following – Wiring to Anti-creep Relay. Faulty Anti-Creep Relay (i.e. permanently energised).
G	 ANTI-SURF FAULT (car door beaks) Car door has been manually released whilst lift in normal service. Fault can also occur if door beak contacts have gone out of alignment. Check the following – Misuse of lift. Car door beak alignment.
I/K	PRE RUN FAULT Fault K - is detected if lift is ready to run (UOK or DOK are ON) but safety chain has been lost at either G4, G5 or G6 <u>without</u> anticreep output set. Fault I - is detected if lift is running in one direction but has 'ready to run' input in opposite direction (i.e. up/down interlock has failed).
R	RESET MODE Lift attempting to reset to bottom floor. If no lift movement or directional arrow shown please check for break in the safety chain.

Rev E: Faults I/K updated – 26/03/2018 – JN – A6144

Rev D: Piccolo 2:1 reference added - 15/03/16 - MH - A5735

Rev C: Fault I added – 11/08/15 – JN – A5688

Rev B: Piccolo fault codes added - 04/08/14 - MH - A5594

Rev A: Fault A description changed - 13/08/13 - JK - A5511



APPENDIX D -TRAILER PCB LAYOUT



APPENDIX E -ESCU PCB TERMINATIONS



APPENDIX F -CONTROL PCB LAYOUT





Introduction:

Prior to setup, the lift must be run at least 5 times with full rated load and ensure the lift is not tight in the guides. It is also advisable to jump up and down a few times in the lift. Finally, ensure the lift is not resetting on the ground.

CALIBRATION ROUTINE (START HERE).

<u>Important note</u>: If ER.01 appears when the load weighing device is first turned ON, ignore and continue with the below calibration.

1 Enter Setup Mode:

1.1 Press and hold the RESET button, then press and hold the ▼ and C buttons and release the reset button, keep ▼ and C pressed until MANU is displayed briefly before showing LEV.

2 Set the Controller with the weight of the empty car:

- 2.1 Press ▼ to move to the TARE function (the TARE value is the car's own weight set to 0)
- 2.2 Empty lift car
- 2.3 Press E and display will show 0.
- 2.4 Press **E** again to start 60 second countdown (T-60 to T-0) to allow time for the installer to exit the car (Ensure there is no extra load in the car during this time)
- 2.5 Measurement is complete when MEMD is briefly displayed and then TARE is shown again

3 Calibration of Load Sensor Controller:

- 3.1 Press ▼ until the HI function is shown (the HI value is used to calibrate the load sensor with a known load)
- 3.2 Press E to select mode
- 3.3 Press \blacktriangle or \triangledown buttons to move value to 400kg
- 3.4 Add 400*kg* of test weight to the cabin. Load must be distributed such that 100*kg* is placed in each of the 4 corners / quadrants of the cabin.
- 3.5 Press **E** to start 60 second countdown (T-60 to T-0) to allow time for the installer to exit the car (Ensure there is no extra load in the car during this time).

IMPORTANT NOTE: For Piccolo models only, allow the Fermator cabin and landing doors to close for duration of this 60 second countdown. This will allow the Load Sensor Controller to evaluate maximum load condition.

APPENDIX H 1 OF 2 LOAD WEIGHING

DEVICE SETUP

- 3.6 Measurement is complete when MEM□ is briefly displayed and then HI is shown again.
- 3.7 Remove test weights.

Continued on page 2 of 2...

4 Set Maximum Rated Load:

- 4.1 Press ▼ until the **FSCA** function is shown (the **FSCA** value is the maximum rated load)
- 4.2 Press **E** to select mode
- 4.3 Press \blacktriangle or \triangledown buttons to move value to 400kg
- 4.4 Press **E** to confirm, **FSCA** is shown again.

5 Set Overload Alarm:

- 5.1 Press ▼ to activate the **LEV1** mode (the **LEV1** value is a percentage of the maximum rated load that will activate the overload alarm)
- 5.2 Press **E** to select mode
- 5.3 Press ▲ or ▼ buttons to move value to 120%
- 5.4 Press E to confirm input. Display will return to LEV1.
- 5.5 LEV2 and LEV3 are not used.

6 Exit Setup Mode

6.1 Press **C** to end calibration and return to normal running. Display will show SAVE briefly.

7 Check Readout

- 7.1 Step into car and check the load value has increased by the installers approximate weight.
- 8 Exit the lift car and check display shows 0. If not, the unit can be zeroed by leaning into the empty lift car and pressing **'C'** briefly.

Note: Pressing the C button will save the setup at any time. To return to the setup menu follow step 1.1 above and use the ▲ or ▼ buttons to move to the required setting. Fault Codes

Code	Meaning
ER.01	Negative Load: ER01 indication is displayed alternatively to the
	measured load (the minus is displayed only up to three numbers, i.e.
	-999). Check connections and recalibrate.
ER.22	Conversion slope not correct: too high signal from 942 Strain Link (fix
	942 to a more rigid part of the lift frame or substitute it). Verify that HI
	value is entered with the right resolution (use weight at least 80%
	FSCA).
ER.23	HI value is too low (in engineering units). HI-Tare must be > 10
ER.24	Calibration Load is too low. Increase load.
ER.26	TARE and HI values identical, in engineering units
ER.28	Overrange / Underrange: ER.28 is displayed alternatively to
	measured load. Verify that sensor mechanical installation is OK and
	corresponding to Factory indications. In case perform again Sensor
	Installation. Calibrate again the 699Plus after the modifications.
ER.30	C pushbutton is detected pressed for more than 3 seconds, when
	controller is in programming.

2 OF 2 LOAD WEIGHING

DEVICE SETUP

<u>MOTOR CALIBRATION PROCEDURE</u> IT IS ACCEPTED THAT PERSONS CARRYING OUT THIS INSTALLATION HAVE ALREADY RECEIVED FORMAL TRAINING. THIS PROCEDURE IS FOR GUIDANCE ONLY.

PREPARATION

ENSURE ALL SAFETY DEVICES ARE INSTALLED AND ARE FUNCTIONING CORRECTLY. IT IS RECOMMENDED THAT BOTH THE PENDANT CONTROLLER AND DDU/SPEAKER BOX ARE USED DURING THIS PROCEDURE.

BEFORE STARTING ENSURE THE VALVE BLOCK IS CORRECTLY SETUP AND THE LIFT IS RUNNING AT RATED SPEED.



FOR BEST RESULTS THE FOLLOWING PROCEDURE SHOULD BE CARRIED OUT WITH APPROXIMATELY 80KG ON THE CARRIAGE.

STEP 1

POSITION LIFT AT BOTTOM FLOOR LEVEL AND ENSURE RESET FLAG IS INSTALLED.

STEP 2

TURN ON SWITCH 1 TO SELECT CALIBRATION MODE AND RESET LIFT CONTROLLER. EITHER BY POWER CYCLE OR USE OF 'RESET'BUTTON ON CARRIAGE.

STEP 3

WAIT FOR THE LEARN LEDS TO FLASH AND A CHARACTER 'C' TO BE DISPLAYED ON THE DDU'S.

STEP 4

PRESS AND HOLD RUN BUTTON; MOMENTARILY PRESS PENDANT BUTTON 4 TO INITIATE CALIBRATION. (NOTE: RUN BUTTON WILL NEED TO BE MAINTAINED)

THE LIFT WILL AUTOMATICALLY RUN UP APPROXIMATELY 1 METER, STOP AND RUN DOWN APPROXIMATELY HALF A METER.

STEP 5

THE LEARN LEDS WILL FLASH TWICE AND THEN REMAIN ON, THIS CONFIRMS THE PUMP UNIT HAS BEEN SUCCESSFULLY CALIBRATED.

STEP 6

RELEASE RUN BUTTON AND TURN OFF **SWITCH 1** TO COMPLETE CALIBRATION MODE AND RETURN TO NORMAL OPERATION.

STEP 7

REFER TO LEARN MODE PROCEDURE (APPENDIX C) IF FLOOR LEVELS REQUIRE PROGRAMMING.

APPENDIX I MIDILIFT SL + MOTOR CALIBRATION PROCEDURE

BEFORE BEGINNING SET-UP GUIDE, ENSURE PLATFORM IS POSITIONED AT APPROPRIATE FLOOR.

Label Neptis Power Door Operator - Quick setup guide

1. Connect the programmer to the door operator.

If this is the first time your digital programmer has been used, it will automatically establish communication with the NEPTIS operator. (Move to step 2).

If your digital programmer has been used previously on a different NEPTIS, it will display the message "NO COMMUNICATION", in which case, please use the following procedure:

A.Press the SET button for about 5 seconds to enter the programming menu. B. Scroll through using the F1 button until you reach the RS485 symbol.

C.Press the ENTER button to enter the "Serial communication setup" section.

D. The digital programmer will establish communication with the operator. Once finished it will display the message "---OK--- Automatic Door Acquired".

E. Press the Exit button to return to the Main Menu.

2. Complete a Learning Cycle.

A.Ensure the end-cap switch is in Position 1.

B. Press and hold the SET button for about 5 seconds to enter the main menu.

C.From the main menu, select the SET UP icon and press ENTER

D.Enter the password. The default password is "AAAAAAAAAA"

E. Please complete the set-up as follows:

S.01	=	OFF
S.02	=	ON
S.03	=	ON
S.04	=	OFF
S.05	=	OFF
S.06	=	OFF
S.10	=	ON

F. The screen will display the following message:

"Operator ready to set up. Press OK to start. A 3 second sound means set up is complete".

G.Manually unlock the landing door (using lock release key) and press OK.

The door will begin to open, searching for a physical stop. Upon reaching the fully open position (when it hits the physical stop), it will emit a prolonged beep. The door will then close at which point the lock can be released. Learn cycle is now completed.

3. Configure door operation.

Enter the main menu, scroll right once and press ENTER to go into the "Switches and Potentiometers" menu. Adjust the following parameters only.

P.01 - Open Speed	=	30%		
P.02 - Close Speed	=	30%		
P.05 - Open Pause Time = 12% (10)		12% (100	% = 60secs max)	
P.13 - Slowing Distance Closing	=	40%.		
P.14 - Closing Assistance Position	=	5%.	NAME: J.NICHOLLS	DATE: 24/10/16
P 15 - Closing Assistance Trust	_	50%	CHECKED: M.HOOD	DATE: 24/10/16
P.18 - Open Distance Vs Physical Stop = 0% .		MIDILIFT SL+		
Important Note: Do not amend any other parameters.			QUICK SETUP GUIDE	
			Stannah	HEAD OFFICE: Anton Mill Andover Hampshire SP10 2NX England Tel: 01264 339090 Eax: 337942

DRAWING NO: APPENDIX J

REV: